

## Frequency Response of BJT Amplifiers

### Low-Frequency Response of BJT Amplifiers:

For the **high-pass filter** circuit of Fig. 14-1a, the output and the input voltages are related by the voltage-divider rule in the following manner:

$$V_o = \frac{R V_i}{R + X_C},$$

with the magnitude of  $V_o$  determined by

$$|V_o| = \frac{R |V_i|}{\sqrt{R^2 + X_C^2}}.$$

For special case where  $X_C = R$ ,

$$|V_o| = \frac{1}{\sqrt{2}} |V_i|, \quad \text{at } X_C = R$$

$$|A_v| = \frac{|V_o|}{|V_i|} = \frac{1}{\sqrt{2}} = 0.707 \quad \text{at } X_C = R$$

In "decibel" (dB):

$$G_{dB} = 20 \log_{10} |V_o| = 20 \log_{10} \frac{1}{\sqrt{2}} = -3 \text{ dB}.$$

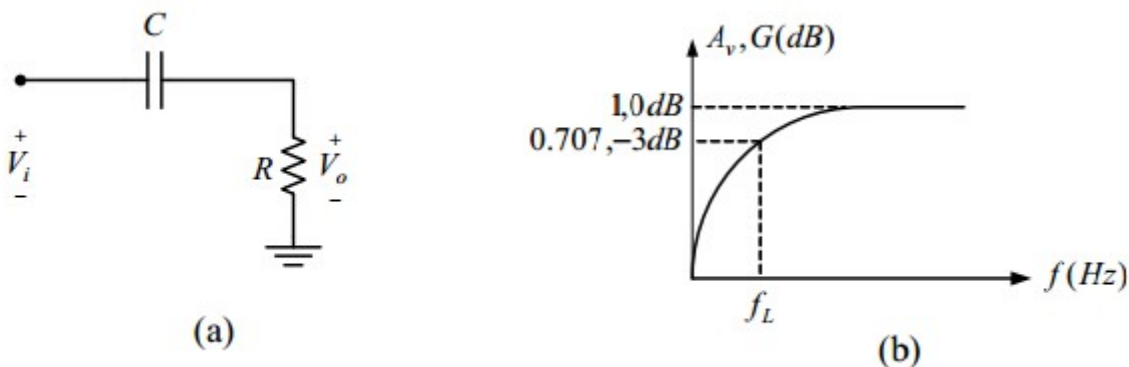


Fig. 14-1

At the frequency of witch  $X_C = R$ , the output will be 70.7 % of the input (a 3 dB drop in gain, see Fig. 14-1b) for the  $RC$  circuit. The frequency ( $f_L$ ) at witch this occurs is determined from:

$$X_c = \frac{1}{\omega c} = \frac{1}{2\pi f C} \Rightarrow$$

$$f_L = \frac{1}{2\pi RC} \quad f_L : \text{the low-cutoff frequency}$$

The Capacitors  $C_S$ ,  $C_C$ , and  $C_E$  will determine the lower-cutoff frequency ( $f_L$ ) of the loaded voltage divider BJT bias configuration shown in Fig. 14-2, but the results can be applied to any BJT configuration.

For the amplifier circuit of Fig. 14-2:

The cutoff-frequency of  $C_S$ ,

$$f_{L_s} = \frac{1}{2\pi R_s R_i C_S}$$

where  $R_i = R_1 \parallel R_2 \parallel h_{ie}$

$$R_i = R_1 \parallel R_2$$

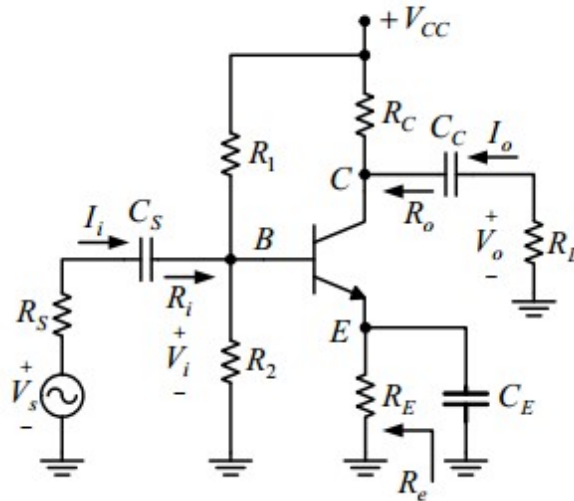


Fig. 14-2

The cutoff-frequency of  $C_C$ ,

$$f_{L_c} = \frac{1}{2\pi R_L R_o C_C}$$

where  $R_o = 1 \parallel h_{oe}$

The cutoff-frequency of  $C_E$ ,

$$f_{L_e} = \frac{1}{2\pi R_e C_E}$$

where  $R_e = R_E \parallel \frac{R_s \parallel h_{ie}}{h_{fe} + 1}$

$$R_s = R_s \parallel R$$

The lower-cutoff frequency,

$$f_L \text{ Max. } f_{L_s}, f_{L_c}, f_{L_E}$$

**Miller's Theorem and Its Dual:**

For the circuit of Fig. 14-3a,

$$\begin{aligned}
 & \begin{array}{c} A_v \\ 1 - \oplus V \\ \oplus \\ \oplus i \\ \oplus \end{array} \\
 I_i &= \frac{V_i}{Z_i}, I_1 = \frac{V_i}{R_i}, I_2 = \frac{V_i - V_o}{Z_F} = \frac{V_i - A_v V_i}{Z_F} \oplus \\
 I_i &= I_1 + I_2 \Rightarrow \frac{V_i}{Z_i} = \frac{V_i}{R_i} + \frac{V_i}{Z_F} (1 - A_v) \Rightarrow \frac{1}{Z_i} = \frac{1}{R_i} + \frac{1}{Z_F} (1 - A_v)
 \end{aligned}$$

when  $Z_F = R_F \Rightarrow \frac{1}{Z_i} = \frac{1}{R_i} + \frac{1}{R_{Mi}}$ , where  $R_{Mi} = \frac{R_F}{1 - A_v}$ .

As shown in Fig. 14-3b,

$$\begin{aligned}
 & \begin{array}{c} 1 - A \\ \omega \oplus \oplus v \oplus C_F \Rightarrow \\ \oplus \end{array} \\
 \text{when } Z_F &= X_{C_F} \Rightarrow \frac{1}{Z_i} = \frac{1}{R_i} + \frac{1}{X_{C_{Mi}}}, X_{C_{Mi}} = \frac{X_{C_F}}{1 - A_v} \oplus
 \end{aligned}$$

$$\begin{array}{c} 1 - A \\ \oplus \oplus v \oplus C_F \\ C_{Mi} \oplus \end{array}$$

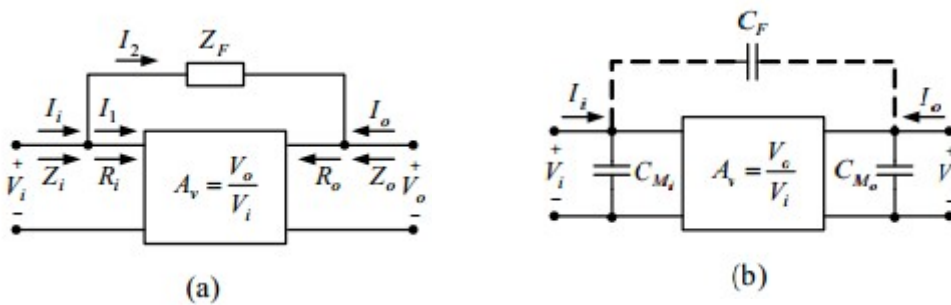


Fig. 14-3

In a similar way

$$\frac{1}{Z_o} = \frac{1}{Z_o} + \frac{1}{Z_F} (1 - A_v) \Rightarrow R_{Mo} = \frac{R_F}{1 - A_v} \oplus$$

$$\omega \frac{1 - A_v}{1 - A_v} v_i C_F \Rightarrow$$

$$X_{C_{Mo}} \frac{X_{C_F}}{1 - A_v} \frac{1}{1 - A_v}$$

$$\frac{1 - A_v}{1 - A_v} v_i C_F$$

$$C_{Mo} \frac{1}{1 - A_v}$$

The above shows us that:

For any **inverting** amplifier (phase shift of 180° between input and output resulting in a negative value for  $A_v$ ), the input and output capacitance will be increased by a Miller effect capacitance sensitive to the gain of the amplifier and the inter electrode capacitance connected between the input and output terminals of the active device.

**High-Frequency Response of BJT Amplifiers:**

A frequency response of the **low-pass filter** circuit of Fig. 14-4a is given by Fig. 14-4b, where the high-cutoff frequency is determined from:

$$f_H \approx \frac{1}{2\pi RC} \quad f_H: \text{the high-cutoff frequency.}$$

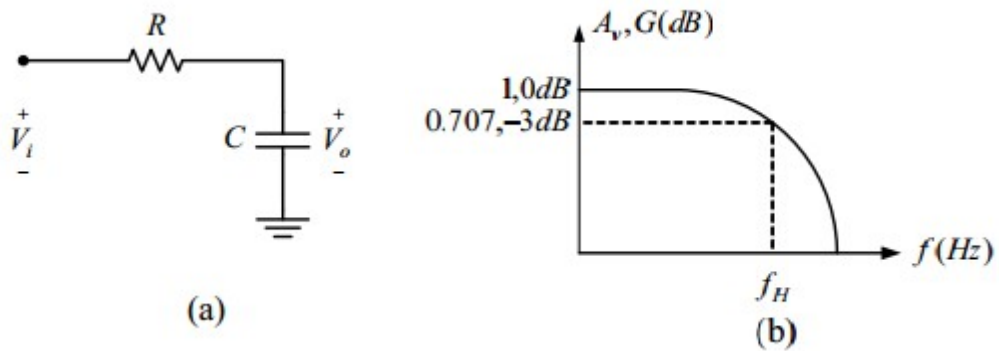


Fig. 14-4

At the high-frequency end, there are two factors that will define the -3 dB point: the circuit capacitance (parasitic and introduced) and the frequency dependence of  $h_{fe}$

**Circuit (Capacitances) Parameters:**

In high-frequency region the capacitive elements of the importance are the inter-electrode (between terminals) capacitances internal to the active device and the wiring capacitance between leads of the circuit. In Fig. 14-5, the various parasitic capacitances ( $C_{be}$ ,  $C_{bc}$ , and  $C_{ce}$ ) of the transistor have been included with the wiring capacitances  $C_{wi}$  and  $C_{wo}$  introduced during construction.

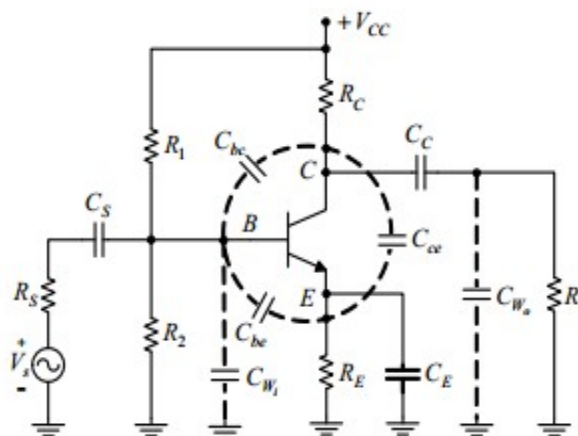


Fig. 14-5





The high-frequency equivalent model for the amplifier circuit of Fig. 14-5 appears in Fig. 14-6. Note the absence of the capacitors  $C_S$ ,  $C_C$ , and  $C_E$ , which are all assumed to be in the short circuit state at these frequencies.

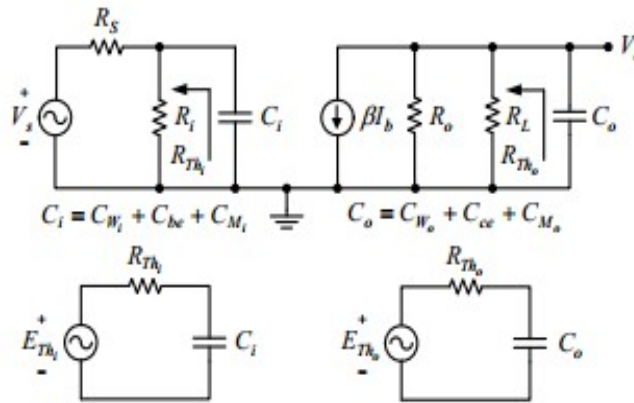


Fig. 14-6

For the circuit of Fig. 14-6:

The input high cutoff frequency,

$$f_{H_i} \approx \frac{1}{2\pi R_{Th_i} C_i}$$

where  $R_{Th_i} \approx R_s \parallel R_i$ ,  $R_i \approx R_1 \parallel R_2 \parallel h_{ie}$ .

$$C_i \approx C_{W_i} \parallel C_{be} \parallel C_{M_i} \parallel C_{W_i} \parallel C_{be} \parallel (1 - A_v) C_{bc}$$

The output high cutoff frequency,

$$f_{H_o} \approx \frac{1}{2\pi R_{Th_o} C_o}$$

where  $R_{Th_o} \approx R_L \parallel R_o$ ,  $R_o \approx R_C \parallel 1/h_{oe}$ .

$$C_o \approx C_{W_o} \parallel C_{ce} \parallel C_{M_o} \parallel C_{W_o} \parallel C_{ce} \parallel (1 - 1/A_v) C_{bc}$$

The higher-cutoff frequency,

$$f_H \approx \text{Min. } f_{H_i}, f_{H_o}$$

### $h_{fe} (\beta)$ Variation:

The beta cutoff frequency ( $f_\beta$ ) is another important transistor cutoff frequency. The  $f_\beta$ , the frequency where the  $\beta$  of the transistor drop to 0.707 of its low-frequency value, is given by

$$f_\beta = \frac{1}{2\pi\beta r_e (C_{be} + C_{bc})}$$

If the frequency of operation is increased above the  $f_\beta$  of the transistor, the  $\beta$  will continue to decrease. Eventually, we find a frequency where the  $\beta = 1$ ; this frequency is called the  $f_T$  of the transistor. The  $f_T$  of a transistor is much higher than the  $f_\beta$ . The relation between these two frequencies is

$$f_r \beta \cdot f_\beta \approx h_{fe} \cdot BW \quad f_r: \text{the gain - bandwidth product frequency.}$$

Finally, in data sheet, the CB high-frequency parameters rather than CE parameters are often specified for a transistor. The following equation permits a direct conversion for determining  $f_\beta$  if  $f_\alpha$  and  $\alpha$  are specified.

$$f_\beta = f_\alpha (1 - \alpha)$$

### Example 14-1:

For the BJT amplifier circuit shown in Fig. 14-7, with the following parameters:

$C_{be} = 36 \text{ pF}$ ,  $C_{bc} = 4 \text{ pF}$ ,  $C_{ce} = 1 \text{ pF}$ ,  $C = 6 \text{ pF}$ ,  $C = 8 \text{ pF}$ , and  $r_o = 1/h_{oe} = \infty \Omega$ .  $C_{wi} w_o$

1. Determine  $f_L$ ,  $f_H$ ,  $BW$ ,  $f_\beta$ , and  $f_T$ .
2. Sketch the frequency response.

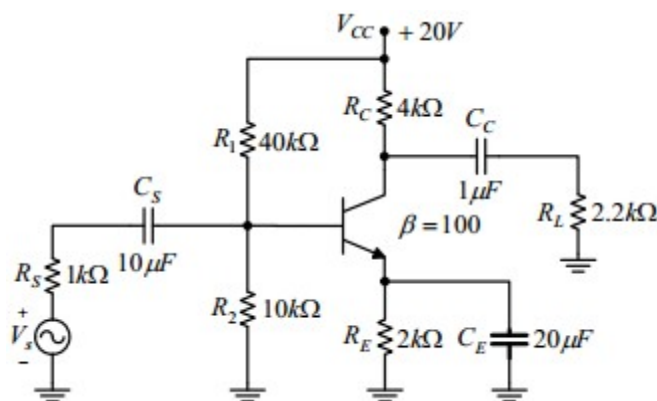


Fig. 14-7

**Solution:**

Testing:  $\beta R_E \geq 10 R_2$ ,  $100 \cdot 2k \geq 10 \cdot 10k$ ,  $200k \Omega \geq 100k \Omega$  Satisfied

$$V_B = \frac{V_{cc} \cdot R_2}{R_1 + R_2} = \frac{20 \cdot 10k}{40k + 10k} = 4V, I_E = \frac{V_E}{R_E} = \frac{V_B - V_{BE}}{R_E} = \frac{4 - 0.7}{2k} = 1.65 mA,$$

$$r_e = \frac{26mV}{I_E} = \frac{26mV}{1.65mA} = 15.76 \Omega, \quad h_{ie} = \beta r_e = 100 \cdot 15.76 \Omega = 1.58 k\Omega.$$

$$A_{v_{mid}} = \frac{-R_L \parallel R_C}{r_e} = \frac{-2.2k \parallel 4k}{15.76} = -90$$

$$R_i = R_1 \parallel R_2 \parallel h_{ie} = 40k \parallel 10k \parallel 1.58k = 1.32 k\Omega$$

$$f_{L_s} = \frac{1}{2\pi R_s \parallel R_i \parallel C_S} = \frac{1}{2\pi \cdot 1k \parallel 1.32k \parallel 10\mu} = 7 Hz$$

$$R_o = R_C \parallel h_{oe} = 4k \Omega,$$

$$f_{L_c} = \frac{1}{2\pi R_L \parallel R_o \parallel C_C} = \frac{1}{2\pi \cdot 2.2k \parallel 4k \parallel 1\mu} = 26 Hz$$

$$R_S = R_S \parallel R_1 \parallel R_2 = 1k \parallel 40k \parallel 10k = 0.89 k\Omega$$

$$R_e = R_E \parallel \left( \frac{R_S}{\beta} \parallel r_e \right) = 2k \parallel \left( \frac{0.89k}{100} \parallel 15.76 \right) = 24.35 \Omega$$

$$f_{L_E} = \frac{1}{2\pi R_e C_E} = \frac{1}{2\pi \cdot 24.35 \parallel 20\mu} = 327 Hz$$

The lower-cutoff frequency,  $f_L = \text{Max. } \{ f_{L_s}, f_{L_c}, f_{L_E} \}$

$$\oplus \text{Max. } \{ 7, 26, 327 \} = 327 Hz$$

$$R_{Th} = R_S \parallel R_i = 1k \parallel 1.32k = 0.57 k\Omega.$$

$$C_i = C_{W_i} \parallel C_{be} \parallel C_{M_i} \parallel C_{W_i} \parallel C_{be} \parallel (1 - A_v) C_{bc} = 6P \parallel 36P \parallel 1 \parallel 90 \parallel 4P \parallel 406 PF$$

$$f_{H_i} = \frac{1}{2\pi R_{Th_i} C_i} = \frac{1}{2\pi (0.57k) (406P)} = 687.732 \text{ Hz}.$$

$$R_{Th_o} = R_L \parallel R_o = 2.2k \parallel 4k = 1.42k \Omega.$$

$$C_o = C_{W_o} \parallel C_{ce} \parallel C_{M_o} \parallel C_{W_o} \parallel C_{ce} \parallel (1 - 1) A_v \parallel C_{bc} = 8P \parallel 1P \parallel 1 \parallel \frac{1}{90} \parallel 4P = 13PF.$$

$$f_{H_o} = \frac{1}{2\pi R_{Th_o} C_o} = \frac{1}{2\pi (1.42k) (13P)} = 8.622 \text{ MHz}.$$

The higher-cutoff frequency,  $f_H = \text{Min.} (f_{H_i}, f_{H_o})$

$$\text{Min.} (687.732, 8.622 \text{ M}) = 687.732 \text{ kHz}.$$

The bandwidth,  $BW = f_H - f_L = 687.732 \text{ k} - 327 = 687.405 \text{ kHz}.$

The beta cutoff frequency,  $f_B \approx \frac{1}{2\pi\beta r_e (C_{be} + C_{bc})}$

$$\approx \frac{1}{2\pi \cdot 100 \cdot 15.76 \cdot 36 \text{ pF} + 4 \text{ pF}} = 2.52 \text{ MHz}$$

The gain-bandwidth product,  $f_T \approx \beta f_B \approx 100 \cdot 2.52 \text{ MHz} = 252 \text{ MHz}$ .

The frequency response for the low- and high-frequency regions, bandwidth, beta cutoff frequency, and gain-bandwidth product frequency are shown in Fig. 14-8

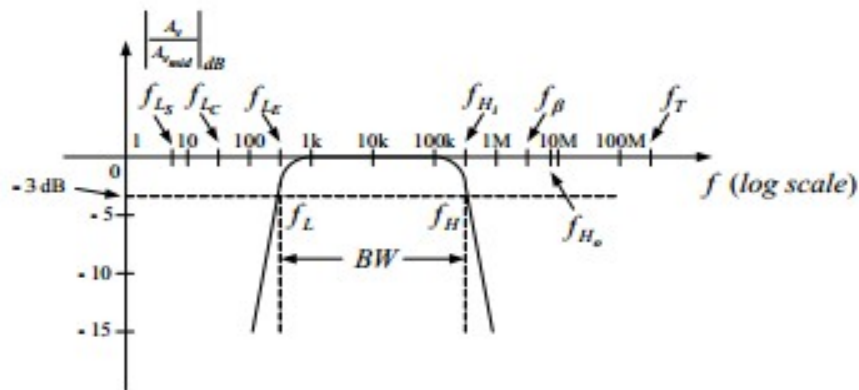


Fig. 14-8

**Exercise:**

For the BJT amplifier circuit of Fig. 14-9, determine the lower- and higher-cutoff frequencies.

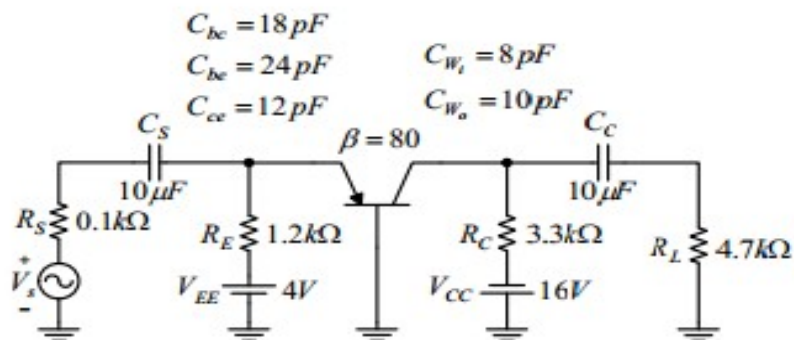


Fig. 14-9